

The THz image resolution enhancement algorithm based on PSF

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Abstract: In recent years, terahertz (THz) imaging technology has received increased attention owing to the promising imaging tools now available for nondestructive testing. However, theoretical models of THz imaging systems are yet to be developed. In this study, we proposed a comprehensive mathematical modeling and simulation theory for the THz imaging system. Gaussian beam distribution was used in the mathematical modeling of the point spread function (PSF). The target function was convolved using the PSF, and the analog transmission of THz images was realized. The PSF of the imaging system was calculated using the optical imaging method. Next, the image was deconvolution-enhanced using the PSF. The image restoration results revealed that the image resolution improved. The restored image contains more details.

Key words: terahertz (THz) imaging, point spread function, image resolution, transmission imaging, deconvolution

基于 PSF 的太赫兹图像分辨率增强算法

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摘要: 近年来, 太赫兹成像技术在多个领域具有广阔的应用。一套完整的太赫兹成像系统的数学模型是非常有必要的。基于点扩散函数的太赫兹图像增强模型是很好的选择。该方法将目标函数与点扩散函数进行卷积, 实现了太赫兹图像的模拟传输。然后根据光学成像的过程, 计算成像系统的点扩散函数。最后, 基于点扩散函数对图像进行反卷积增强。该模型用于探测图像增强的结果表明, 该方法有效地提高了图像的分辨率。恢复的映像包含更多细节。

关键词: 太赫兹成像; 点扩散函数; 图像增强; 透射成像; 反卷积

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Introduction

Terahertz (THz) imaging technology has received increased attention in recent years. The ability of THz beams to penetrate nonmetallic materials enables the formation of transmitted images similar to X-rays. The THz beam is nonionized, and the system can be safely operated. Therefore, these systems are promising imaging tools for nondestructive testing in fields such as medical imaging^[1], encapsulated integrated circuit certification^[2-3], nondestructive testing of cultural relics^[4], and thickness measurement^[5-6]. Despite its wide range of applications, this type of imaging system still constitutes an emerging field in imaging science. The generation and detection of THz electromagnetic radiation were not commercially

available until a few decades ago. THz imagery was developed less than 20 years ago^[7-8]. This type of imaging system is still in the nascent stage, and the perfect imaging equation has not been established yet. Their theoretical models are yet to be developed^[9]. Perfect imaging theory and model are indispensable for advanced research on THz optics and image reconstruction.

1 Point spread function mathematical model

The resolution of an object in an optical imaging system decreases with an increase in the wavelength. The THz wave has a large wavelength ($\lambda = 0.3 \text{ mm}$ at $f = 1 \text{ THz}$). The diameter of the point spread function (PSF)

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and the diffraction-limited resolution are directly related to the wavelength. THz systems with higher signal-to-noise ratios (SNRs) have been developed to achieve better resolution and a larger depth of penetration. However, a trade-off between the resolution and wavelength of the light source is unavoidable. Point diffusion refers to the scattering of light energy encountered in a point light source. If an object is assumed to be a point, the image of the object is at least the width of a reflected point. However, the image of an object is usually made up of a speck of several reflection points. The central part of the speck is the brightest, and the brightness decreases as we move away from the central region. The more concentrated the blob, the better the image resolution. THz imaging equations are formulated using the PSF.

Due to the interaction of the light waves with the optical system, the incident light exhibits diffraction or scattering phenomenon, that is, the ideal point on the object plane is no longer the ideal point on the image plane. Mathematically, a two-dimensional (2D) δ function (impulse function) is used to represent the point light source. The intensity distribution of the output image is known as the impulse response. In incoherent-illumination imaging systems (e. g. , fluorescence microscopy), the imaging process follows spatial translation invariance and satisfies the superposition principle of linear systems. The imaging process for a point can be considered as the convolution of a real point by using the PSF. For common optical systems (wherein all the lenses are ideal lenses and possess circular symmetry, i. e. , all the lenses have a circular aperture), the ideal PSF corresponding to the point source on the axis on the object plane is often identified as an airy disk on the image plane and is represented by the diffraction pattern of concentric rings around the central bright spot, as shown in Fig. 1. However, in practice, spatial translational invariance is an ideal condition that no practical imaging system can satisfy, but this condition is reasonable for high-quality research instruments.

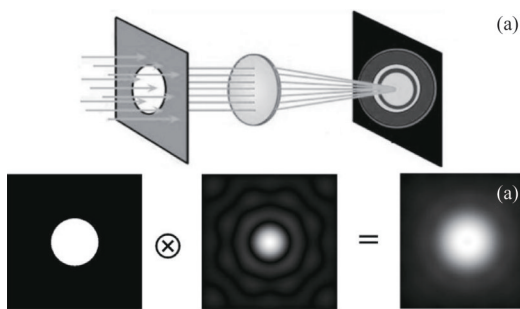


Fig. 1 Convolution imaging of a point and the PSF (airy disk) (a) schematic of airy disk formation, (b) convolution imaging diagram of a point and the PSF.

图1 点与PSF (Airy Disk)的卷积成像(a)艾里斑形成示意图, (b)点与PSF的卷积成像图

An imaging system can be regarded as a linear shift-invariant system that transforms the ideal image into the image that one observes. The transformation process in-

volves the convolution of the real object image and point diffusion image. The object transmittance function of the object transmittance plane can be mathematically expressed as follows:

$$O(u_o, v_o) = \iint O(x, y) \delta(u_o - x, v_o - y) dx dy, \quad (1)$$

where $O(u, v)$ is the object transmittance function, $O(x, y)$ represents the object plane, and $\delta(u_o - x, v_o - y)$ denotes the 2D δ function. Figuratively speaking, the 2D δ function is a cuboid in space, and the volume of the cuboid is 1.

In transmission imaging, the image plane domain is calculated as the superposition of each impulse function image, that is, as weighted PSF of the image plane; the superposition of the same weight functions is used in the object plane. Each point on the object surface ($O(u, v)$) is abstracted as a spatial impulse function. The image of this point on the image plane is the convolution of the spatial impulse function with the PSF of the imaging system. Because the imaging system has different PSF for different frequency bands, the PSF of all frequency bands must be integrated. The image can be mathematically expressed as follows:

$$S(u, v) = \int_{f_1}^{f_2} O(u, v) \otimes PSF(u, v, f) df, \quad (2)$$

where $S(u, v)$ denotes the image of the point in the imaging system, and $PSF(u, v, f)$ denotes the image of the 2D δ function. f_1 and f_2 are, respectively the start and end frequencies of the light source.

In the imaging system proposed in this paper, the frequency of the light source is set as 2.52 THz ($\lambda = 0.118$ mm), and the output of the system is a Gaussian beam. After passing through two lenses, the beam becomes a collimating beam with a diameter of 80 mm. This collimating beam then passes through the object and shines into the THz camera. The Microxcam384 THz uncooled bolometric camera from INO is used in the proposed system. The primary parameters of this camera are as follows: a 384×288 -pixel sensor with a pixel pitch of $35 \mu\text{m}$, wavelength range: $70\text{--}3198 \mu\text{m}$ ($4.25\text{--}0.094$ THz), F-number: 0.7, focal length: 44 mm, object distance is 600 mm to infinity^[10-11]. The proposed THz imaging setup is illustrated in Fig. 2.

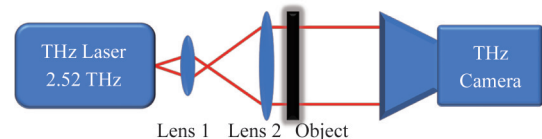


Fig. 2 Schematic of the THz imaging setup
图2 太赫兹成像装置原理图

In Fig. 2, lens 1 and lens 2 uniformly expand the beam to produce a smooth illumination area without interference fringes.

In the imaging system illustrated in Fig. 2, the magnification of the THz camera lens is set as 1:1.56. At this magnification, each pixel of the object's surface is

approximately $54.6 \mu\text{m}$ ($35 \mu\text{m} \times 1.56$). Under the 2.52-THz irradiation, the aperture of $54.6 \mu\text{m}$ is close to the diffraction limit. According to the Huygens - Fresnel principle, an aperture of this size can be treated as a point light source. This point light source produces a spherical wave that is captured by the lens of the THz camera and is refocused on the image plane to form a blurred point. This causes image blurring.

We simulated the point by using a Gaussian beam. The spot diameter of a Gaussian beam is the diameter at which the beam intensity drops to $1/e^2$ of the peak value. The waist radius at a distance between the image point and the point source Z can be expressed as follows^[12]:

$$h(z,f) = h(0,f) \sqrt{1 + \left(\frac{\lambda z}{\pi h^2(0,f)}\right)^2}, \quad (3)$$

where $h(0, f)$ is the spot radius at the center of the beam, and f is the frequency of the beam. The intensity

$$PSF(z,f) = I_0 \exp\left[-2(u^2 + v^2) / \left(\frac{0.565}{\sqrt{2\ln 2}} \frac{k}{NA} \frac{c}{f} \sqrt{1 + \left(\frac{2\ln 2}{c\pi} \left(\frac{NA}{0.565k}\right)^2 f z\right)^2}\right)^2\right], \quad (7)$$

where $I_0 = I(0, 0, z, f)$ denotes the intensity at the center of the beam.

In the proposed imaging system, the light source is a single-frequency laser ($f = 2.52 \text{ THz}$); thus, the inte-

$$S(\rho) = O(\rho) \otimes I_0 \exp\left[-2\rho^2 / \left(\frac{0.565}{\sqrt{2\ln 2}} \frac{k}{NA} \frac{c}{f} \sqrt{1 + \left(\frac{2\ln 2}{c\pi} \left(\frac{NA}{0.565k}\right)^2 f z\right)^2}\right)^2\right], \quad (8)$$

where $\rho = \sqrt{u^2 + v^2}$ is the radial distance between a point in the z -plane and the center of the beam. The output of the convolution operation is the simulated THz image.

2 THz image restoration by using PSF

The parameters of the THz imaging system are as follows: $NA = 0.022$, $f = 2.52 \text{ THz}$, pupil diameter = 70 mm, focal length = 44 mm, $k = 0.76$, and object distance = 736 mm. First, by using Eq. 8, we compared the simulated image and the measured image of the spot with an aperture of 0.3 mm. For test point imaging, we employed the integral average method to reduce random noise and set the number of integrals as 50. The calculation results and test results of point imaging are shown in Fig. 3.

As can be seen from Fig. 3, the calculation results were similar to the test results and within the allowable error range. This highlights that the PSF equation established in this paper can be used. Many factors affect the imaging quality in transmission imaging, which cannot be discussed in this paper because of space constraints. However, the comparison of the computed and tested images of points revealed that PSF has a considerable effect. This confirms the previously mentioned point that the transmission imaging result of a target can be obtained as the convolution of the transmission function of the target by using the PSF. Consequently, the deconvolution of the PSF and the THz image yields a higher-reso-

distribution of the THz beam can be expressed using Gaussian distribution as follows:

$$I(u,v,z,f) = I(0,0,z,f) \exp\left(-2(u^2 + v^2)/w(z,f)^2\right). \quad (4)$$

The full width at half maxima (FWHM) for the aforementioned Gaussian distribution (Eq. 4) can be obtained as follows:

$$FWHM(z,f) = \sqrt{2\ln 2} h(z,f) \quad . \quad (5)$$

The FWHM of diffraction-limited focused spot can be expressed as follows:

$$FWHM(0,f) = 0.565 \frac{k}{NA} \lambda \quad , \quad (6)$$

where k depends on the truncation ratio and irradiance level, NA is the numerical aperture, and λ is the wavelength. Substituting Eqs. 3, 5, and 6 into Eq. 4, the relationship between PSF (z, f) and the physical parameters of the system can be expressed as follows:

gral of frequency parameter f can be removed in Eq. 2. Accordingly, the transfer function of the proposed THz imaging system can be expressed as follows:

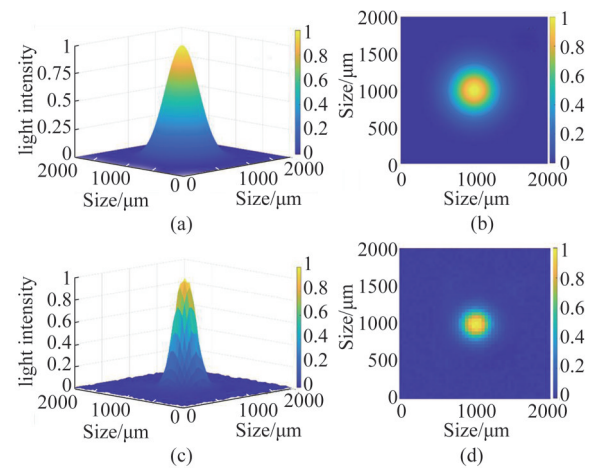


Fig. 3 Simulation and test of 0.3-mm point imaging (All data are normalized and displayed in false color for ease of understanding) (a) the point imaging 3D map obtained using Eq. 8, (b) the point imaging 2D map obtained using Eq. 8, (c) the point imaging 3D map, (d) the point imaging 2D map
图3 直径0.3 mm小孔成像的仿真与测试(所有数据均归一化,并采用伪彩色显示)(a)方程(8)计算的小孔成像三维显示图,(b)方程(8)计算的小孔的像,(c)测试的小孔成像三维显示图,(d)测试的小孔成像二维显示图

lution representation of the object. The algorithm can be mathematically expressed as follows^[13-15]:

$$O(u,v) = S(u,v) \otimes^{-1} PSF \quad . \quad (9)$$

By using Eqs. 8 and 9, we restored the image of a simple transmission resolution plate. The result is shown in Fig. 4.

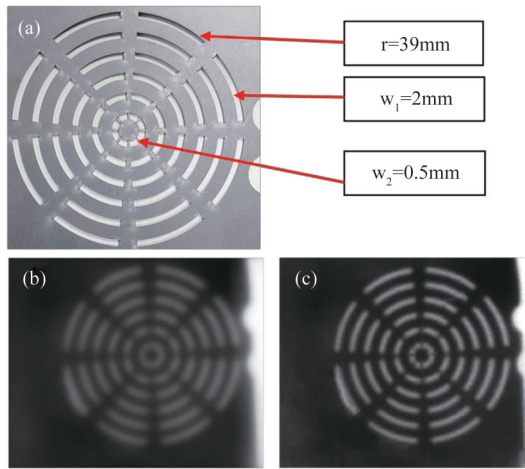


Fig. 4 Image restoration by using the PSF (a) schematic of a simple resolution plate size, where R denotes the radius of the largest circle, w_1 is the width of the light transmittance gap, w_2 is the width of the narrowest part of the mask, and dimension error is ± 0.01 mm, (b) the original image outputted by the camera, (c) the image restored using the PSF

图4 基于PSF的图像增强 (a)简单的分辨率板尺寸图,其中 R 为最大圆的半径, w_1 为镂空间隙的宽度, w_2 为掩模板最窄部分的宽度,所有尺寸误差为 ± 0.01 mm, (b)为相机输出的原始图像, (c)为基于PSF增强后的图像

By comparing Figs. 4(b) and 4(c), it can be seen that from the perspective of visual effect, the proposed image restoration algorithm based on PSF increased the image resolution to a certain extent. The restored image contained more details. The edges became sharper, and finer shades were found. The thin steel sheet connecting the central ring was not clearly visible in the original THz image. The mean square error (MES), SNR, and peak signal to noise ratio (PSNR) of the original THz image and reconstructed image were calculated and are presented in Table 1. The reconstructed images possessed improved MES, SNR, and PSNR.

Table 1 MES, SNR, and PSNR of the original THz image and reconstructed image

表1 原始THz图像和重构后图像与可见光图像之间的MES, SNR和PSNR

	MES	SNR	PSNR
Original THz image	160.042 9	60.392 2	16.382 5
Reconstructed image	39.069 5	86.567 7	27.891 1

3 Conclusions

In this study, we presented a method to improve the THz imaging resolution. This method is based on the fact that the transmission imaging result of the target can be obtained as the convolution of the transmission function of the target by using the PSF. First, the PSF of the imag-

ing system is calculated using the optical imaging method. Next, the image is deconvolution-enhanced using the PSF. Furthermore, the derivation of a clear THz imaging equation and the image reduction results demonstrated that the image resolution improved. In addition, the image possessed location details and structural similarity. The results confirmed that the proposed method could be used to improve the THz image resolution. The reconstructed images possessed improved MES, SNR, and PSNR.

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